Angular distributions and rotations of frames In vector meson decays to lepton pairs

Sandro Palestini, CERN

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Reference frames, angular variables

The z axis is directed along the beam.

The lab frame is oriented so that the J/ ψ is in the x-z plane.

The y and y' axes are parallel.

Different choices are possible for the the direction of z' (and x')



Collision axis

Functional form of the angular distribution for decays of 1⁻⁻ states to lepton pairs decays

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dN/d\Omega \propto [1 + \lambda_{\theta} \cos^{2}(\theta) + \lambda_{\varphi} \sin^{2}(\theta) \cos(2\varphi) + \lambda_{\theta \omega} \sin(2\theta) \cos(\varphi)] / (1 + \lambda_{\theta}/3)
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It is valid in any frame (eg: CS or H, only the y-axis direction is fixed) under general conditions, but of course the three coefficients have different values in different frames:

Rotation of frame as $x'=x \cos(\delta)-z \sin(\delta)$ etc.,

Between CS and H frames, the rotation angles approximates ~ 90 deg over large areas of ATLAS or CMS acceptance

$$1 \Rightarrow 1 + \frac{1}{2}\sin^{2}(\delta) \cdot (\lambda_{\theta} - \lambda_{\varphi}) + \frac{1}{2}\sin(2\delta) \cdot \lambda_{\theta\varphi} = N$$
$$\lambda_{\theta} \Rightarrow \left(1 - \frac{3}{2}\sin^{2}\delta\right)\lambda_{\theta} + \frac{3}{2}\sin^{2}(\delta) \cdot \lambda_{\varphi} - \frac{3}{2}\sin(2\delta) \cdot \lambda_{\theta\varphi} = N\lambda_{\theta}'$$
$$\lambda_{\varphi} \Rightarrow \left(1 - \frac{1}{2}\sin^{2}\delta\right)\lambda_{\varphi} + \frac{1}{2}\sin^{2}(\delta) \cdot \lambda_{\theta} + \frac{1}{2}\sin(2\delta) \cdot \lambda_{\theta\varphi} = N\lambda_{\varphi}'$$
$$\lambda_{\theta\varphi} \Rightarrow \cos(2\delta) \cdot \lambda_{\theta\varphi} + \frac{1}{2}\sin(2\delta) \cdot (\lambda_{\theta} - \lambda_{\varphi}) = N\lambda_{\theta\varphi}'$$

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Modes defined by the coefficients



Acceptance requirements for angular polarization study:

 $\begin{array}{l} \lambda_{\theta}: \text{benefits from large coverage in } \cos(\theta), \\ \quad \text{and coverage in } \phi \text{ to disentagle from } \lambda_{\phi} \text{ (see below)} \\ \lambda_{\phi}: \text{needs coverage in } \phi \text{ for rather small } |\cos(\theta)|. \\ \lambda_{\theta\phi}: \text{needs coverage in } \phi \text{ for } |\cos(\theta)| \approx 0.3\text{-}0.9 \\ & \text{S.P., Vienna, 21 Apr. 2011} \end{array}$

Expected 2D distributions of events in representative bins in y, p_T **Helicity frame**

T Ð

 λ_{ω} : coverage already at low p_{T} $\lambda_{\theta \omega}$ and in particular λ_{θ} : improved coverage in regions of large p_{T} and/or large rapidity

[Monte Carlo with uniform angular distribution generation, ATLAS-inspired acceptance. Negative y, or opposite lepton charge convention give opposite *curvatures*]





2D distributions in representative bins in *y*, *p*_T

C-S frame

Good coverage for $\lambda_{\theta\varphi}$; λ_{θ} and λ_{φ} entangled at low-moderate p_T/y : For $\varphi \approx \pm \pi/2$, we are sensitive to the combination: $(\lambda_{\theta} + \lambda_{\varphi})/(1 - \lambda_{\varphi})$ [not useful if $\lambda_{\theta} \approx - \lambda_{\varphi}$]







 $p_{\rm T}$ = 16 – 18 GeV/c



Illustration of acceptance for intermediate p_{T} , low y



Approximate acceptance as depending on |P_{muon}|

Approximate rotation between frames with 90 deg.

General properties of the coefficients

• From general principles, in any frame:

 $|\lambda_{\theta}| \le 1$, $|\lambda_{\phi}| \le \frac{1}{2}(1+\lambda_{\theta})$.

• Also, for any given set $[\lambda_{\theta}, \lambda_{\phi}, \lambda_{\theta\phi}]$ in a frame F, we could rotate to a new frame F' where $\lambda'_{\theta\phi} = 0$



Rotation in the space of the coefficients

 It is convenient to consider the transformations of the coefficients of the angular distribution under rotation of frame as a geometrical rotation in the 3D space of the coefficients:

The transformations are described as ellipses in the space of the coefficients, normal to the plane $\lambda_{\theta}\lambda_{\phi}$, and wound about the line $\lambda_{\theta} = \lambda_{\phi}, \lambda_{\theta\phi} = 0.$



- A rotation by $\pi/2$ (typical between CS and H frame) links opposite points on the ellipses.
- The ellipses fill a conical volume (we are dealing with inclusive processes ...)
- The conical surface defines the maximum range allowed by for $|\lambda_{\theta\phi}|$ for any given values of λ_{θ} , λ_{ϕ} :

$$|\lambda_{\theta\phi}|^{\max} = \frac{1}{2}\sqrt{(1-\lambda_{\theta})(\lambda_{\theta}+1-2\lambda_{\phi})}$$

 This expression completes the bounds/ consistency relations between coefficients, together with:

$$|\lambda_{\theta}| \le 1$$
, $|\lambda_{\phi}| \le \frac{1}{2}(1+\lambda_{\theta})$

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Bounds/consistency relations between coefficients

• The *conical* bound is tighter than the bounds usually shown.



Invariant combinations of the coefficients

- Relevance of invariants discussed yesterday
- An invariant may be seen as related to a property of an ellipsis, rather than to a point that loops along the ellipsis as frames are rotated.

First example: related to known invariant $\tilde{\lambda}$ The plane containing any ellipsis defines a correlation between λ_{θ} and λ_{φ} : $\lambda_{\phi} - 1 = -(\lambda_{\theta} + 3)/(3 + \tilde{\lambda})$,

in other words: the value of $\tilde{\lambda} = (\lambda_{\theta} + 3\lambda_{\phi})/(1-\lambda_{\phi})$ is invariant.

A new invariant may be related to other properties, such as size of axes of ellipsis, or the range covered by the coefficients. They involve the third coefficient $\lambda_{\theta \omega}$. An example is: $\lambda_{\theta \varphi}$

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$$\lambda^* = \frac{1 + (\lambda_\theta - \lambda_\phi)/4}{\sqrt{(\lambda_\theta - \lambda_\phi)^2 + 4\lambda_{\theta\phi}^2}}.$$



- $\tilde{\lambda}$ specifies a plane, λ^* specifies a cylinder (elliptical)
- Each of them alone does not specify the *intrinsic angular distribution* (but provides a relevant information)
- Together, they specify the intrinsic angular distribution
- The phase along the ellipsis specifies how the intrinsic angular distribution is oriented relative to (*e.g.*) the H and the CS frames

Summary

- A geometrical description for the transformation of the coefficients of the angular distributions under rotations of frames (in the production plane).
- Better bounds/consistency relations between the coefficients.
- A new discussion of invariants, a new invariant depending on the three coefficients of the angular distribution.

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- S.P., PR D83, 031503 (arXiv:1012.2485).
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